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Over the past 50 years, Meriam & Kraige's Engineering Mechanics: Dynamics has established a highly respected tradition of Excellence—A Tradition that emphasizes accuracy, rigor, clarity, and applications. Now completely revised, redesigned, and modernized, the new fifth edition of this classic text builds on these strengths, adding new problems and a more accessible, student-friendly presentation. Solving Dynamics Problems with Matlab If MATLAB is the operating system you need to use for your engineering calculations and problem solving, this reference will be a valuable tutorial for your studies. Written as a guidebook for students in the Engineering Mechanics class, it will help you with your engineering assignments throughout the course. This textbook introduces undergraduate students to engineering dynamics using an innovative approach that is at once accessible and comprehensive. Combining the strengths of both beginner and advanced dynamics texts, this book has students solving dynamics problems from the very start and gradually guides them from the basics to increasingly more challenging topics without ever sacrificing rigor.

Engineering Dynamics spans the full range of mechanics problems, from one-dimensional particle kinematics to three-dimensional rigid-body dynamics, including an introduction to Lagrange's and Kane's methods. It skillfully blends an easy-to-read, conversational style with careful attention to the physics and mathematics of engineering dynamics, and emphasizes the formal systematic notation students need to solve problems correctly and succeed in more advanced courses. This richly illustrated textbook features numerous real-world examples and problems, incorporating a wide range of difficulty; ample use of MATLAB for solving problems; helpful tutorials; suggestions for further reading; and detailed appendixes. Provides an accessible yet rigorous introduction to engineering dynamics Uses an explicit vector-based notation to facilitate understanding Professors: A supplementary Instructor's Manual is available for this book. It is restricted to teachers using the text in courses. For information on how to obtain a copy, refer to: http://press.princeton.edu/class_use/solutions.html

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Most books treat the subject of intermediate or advanced dynamics from an "analytical" point of view; that is, they focus on the techniques for analyzing the

problems presented. This book will present the basic theory by showing how it is used in real-world situations. It will not use software as a black box solution, nor drill the students in problem solving. It will present advanced concepts but in a new way - for example, detailed derivations of Lagrange's equations will be left to references or advanced courses but their utility as an...

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Parallel structures are more effective than serial ones for industrial automation applications that require high precision and stiffness, or a high load capacity relative to robot weight. Although many industrial applications have adopted parallel structures for their design, few textbooks introduce the analysis of such robots in terms of dynamics and control. Filling this gap, *Parallel Robots: Mechanics and Control* presents a systematic approach to analyze the kinematics, dynamics, and control of parallel robots. It brings together analysis and design tools for engineers and researchers who want to design and implement parallel structures in industry. Covers Kinematics, Dynamics, and Control in One Volume The book begins with the representation of motion of robots and the kinematic analysis of parallel manipulators. Moving beyond static positioning, it then examines a systematic approach to performing Jacobian analysis. A special feature of the book is its detailed coverage of the dynamics and control of parallel manipulators. The text examines dynamic analysis using the Newton-Euler method, the principle of virtual work, and the Lagrange formulations. Finally, the book elaborates on the control of parallel robots, considering both motion and force control. It introduces various model-free and model-based controllers and develops robust and adaptive control schemes. It also addresses redundancy resolution schemes in detail. Analysis and Design Tools to Help You Create Parallel Robots In each chapter, the author revisits the same case studies to show how the techniques may be applied. The case studies include a planar cable-driven parallel robot, part of a promising new generation of parallel structures that will allow for larger workspaces. The MATLAB® code used for analysis and simulation is available online. Combining the analysis of kinematics and dynamics with methods of designing controllers, this text offers a holistic introduction for anyone interested in designing and implementing parallel robots.

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